

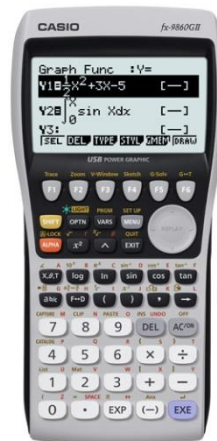
# Engineering Surveyor Programs

Reference Manual

**Revision 4.11 - February 2014**



Casio fx-7400G PLUS



Casio fx-9860GII (SD)



# ENGINEERING SURVEYOR

Engineering Surveyor Programs  
for Casio fx-7400G & fx-9860GII

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**CONTENTS**

INTRODUCTION	3
PROGRAMS	
1.    1PT~CFIX	5
2.    2PT~CFIX	6
3.    3D~CFIX	7
4.    3D~DIST	8
5.    3PT~CFIX	9
6.    ANGLE	10
7.    AREA	11
8.    BRG~DIST	12
9.    CIRCLE	13
10.   COLUMN	14
11.   CURVE	15
12.   CUT~AREA	16
13.   HAVERSIN	17
14.   INT~BEAR	18
15.   INT~DIST	19
16.   INT~LINE	20
17.   LEVELS/LEVELING**	21
18.   LN2PLANE	22
19.   MEAN~XYZ	23
20.   NOTEBOOK	24
21.   OFFSET	25
22.   POLYGON	26
23.   PT2LINE	27
24.   PT2PLANE	28
25.   RADIAL	29
26.   RESECT	30
27.   SURVEY	31
28.   SURVEY2D	32
29.   TRANSFRM	33
30.   TRAVERSE	34
31.   UNI~COLS	35
32.   VECTORS	36
33.   VERTICAL	37
EXAMPLES	38
REVISIONS	48
COPYRIGHT NOTICE	49

## INTRODUCTION

### Instructions

The following pages illustrate the programs contained within the files “my\_progs.fxi” (for fx-7400G) and “fx-9860\_g1m” (for fx-9860GII).

The program files can only be viewed using the “Casio” software that is supplied.

Each program may be uploaded to the Casio individually.

The programs have been tested thoroughly, but any results should be confirmed by other means where possible. These programs are provided free of charge “as-is”. The author does not take any responsibility for any data loss through the use of these programs.

### Manual Programming

Using the program listings, each file may be manually typed into the Casio calculator. However, care should be taken to avoid typographical mistakes, such as distinguishing between 1 & i and 0 (zero) & o.

### Casio Key Sequences

The following shortcuts are quick ways to find various program commands when programming the Casio fx7400g+.

Pol(	OPTN ►F2 ►►F1
If	SHIFT VARS F1 F1
Then	SHIFT VARS F1 F2
Else	SHIFT VARS F1 F3
IfEnd	SHIFT VARS F1 F4
Lbl	SHIFT VARS F3 F1
Goto	SHIFT VARS F3 F2
Fix	SHIFT MENU ►►F1

Engineering Surveyor Programs  
for Casio fx-7400G & fx-9860GII

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Degrees Minutes and Seconds

***Entering Angles***

To enter angles in degrees, minutes and seconds into the Casio fx7400g+, the following key presses are required...

eg 123° 45' 56" (Entered in a program OR in "RUN" mode)

<u>INPUT</u>	<u>DISPLAY</u>
123	123
[OPTN]	
[▶]	
[F2] (ANGL)	
[▶]	
[F1] (°)	123°
45	123° 45
[F1] (')	123° 45'
56	123° 45' 56
[F1] (")	123° 45' 56"
[EXE]	

*To enter a Negative angle, only the degree part needs to be preceded by a "minus" sign. Eg -123°45'56"*

***Converting Decimal Degrees to Deg Min Sec***

The following example converts a decimal degree value into displaying Degrees, Minutes and Seconds.

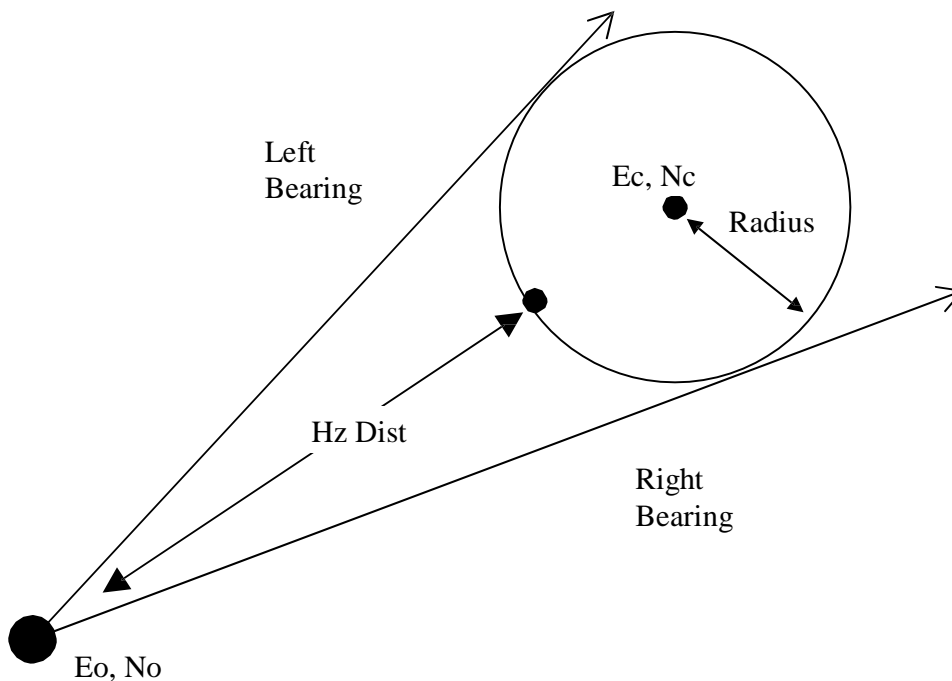
In a Program		In "Run" mode	
Input	Display	Input	Display
	123.456789	123.456789 [EXE]	123.456789
[OPTN]		[OPTN]	
[▶]		[▶]	
[F2]		[F2]	
[▶]		[▶]	
[F2]	123°27'24"	[F2]	123°27'24"

**1PT~CFIX**

Introduction

Calculates the centre of a circle using observed whole circle bearings to both edges and a measured distance to the nearest point in a line through the centre..

Diagram



Input

Station Co-ordinates:	(Eo, No)
Hz Angle to Left Side:	Left Bearing
Hz Angle to Right Side:	Right Bearing
Hz Dist to Centre:	Hz Dist

Output

Centre Co-ordinates:	(Ec, Nc)
Radius:	R
Diameter:	D

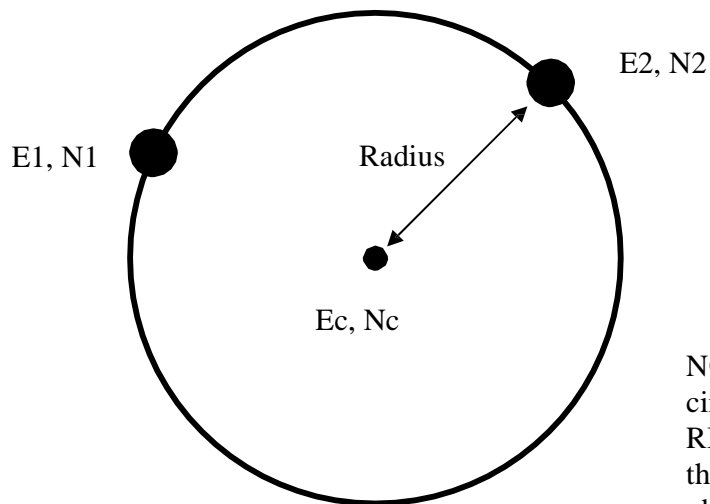
## 2PT~CFIX

### Introduction

Calculates the centre of a circle given the co-ordinates of 2 points on its perimeter.

NOTE: 2 solutions are possible.

### Diagram



NOTE: In this case the circle centre is to the RIGHT of the points in the order they were observed.

### Input

Co-ordinates of 2 known points:	(E1, N1) (E2, N2)
Direction of Centre from points:	Left or Right
Radius:	R

### Output

Centre Co-ordinates:	(E <sub>c</sub> , N <sub>c</sub> )
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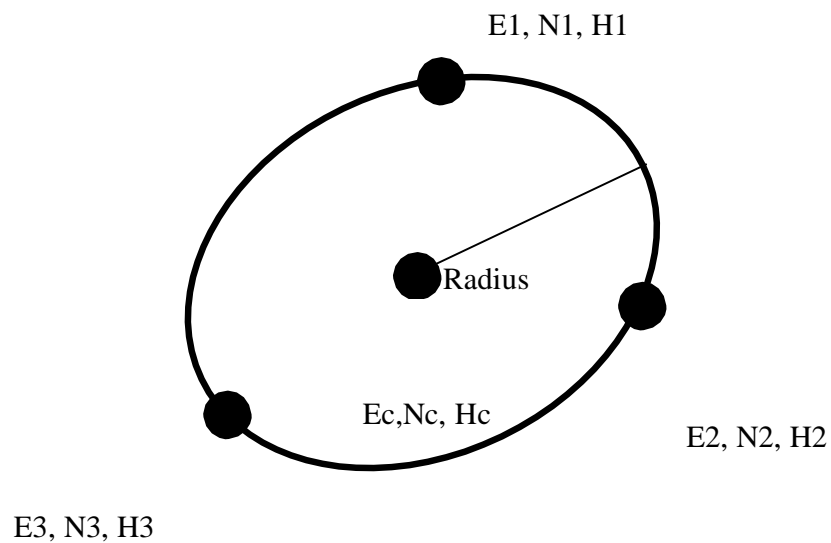
### 3D~CFIX

#### Introduction

Calculates the centre of a circle given the co-ordinates of 3 (x,y,z) points on its perimeter. The circle may be at any angle from any axis.

The points may be input in any order.

#### Diagram



#### Input

3D co-ordinates of 3 known points:  $(E1, N1, H1)$   $(E2, N2, H2)$   
 $(E3, N3, H3)$

#### Output

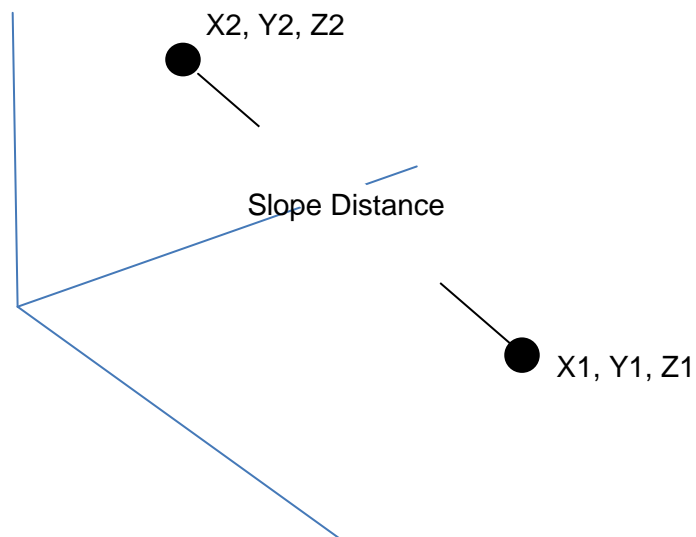
Centre Co-ordinates:  $(E_c, N_c, H_c)$   
Radius:  $R$

### 3D~DIST

#### Introduction

Calculates the slope distance (3D) between 2 3D points (X,Y,Z).  
The differences in X, Y & Z are also shown.

#### Diagram



#### Input

Co-ordinates of 2 known points:  $(X_1, Y_1, Z_1)$  &  $(X_2, Y_2, Z_2)$

#### Output

Differences in X, Y & Z:  $dX, dY$  &  $dZ$   
Slope distance:  $SD$

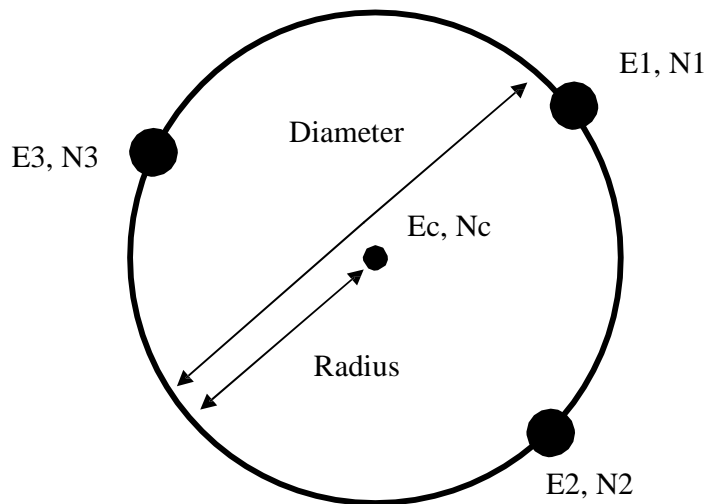


### 3PT~CFIX

#### Introduction

Calculates the centre of a circle given the co-ordinates of 3 points on its perimeter.

#### Diagram



#### Input

Co-ordinates of 3 known points: (E1, N1) (E2, N2) (E3, N3)

#### Output

Centre Co-ordinates: (Ec, Nc)

Radius: R

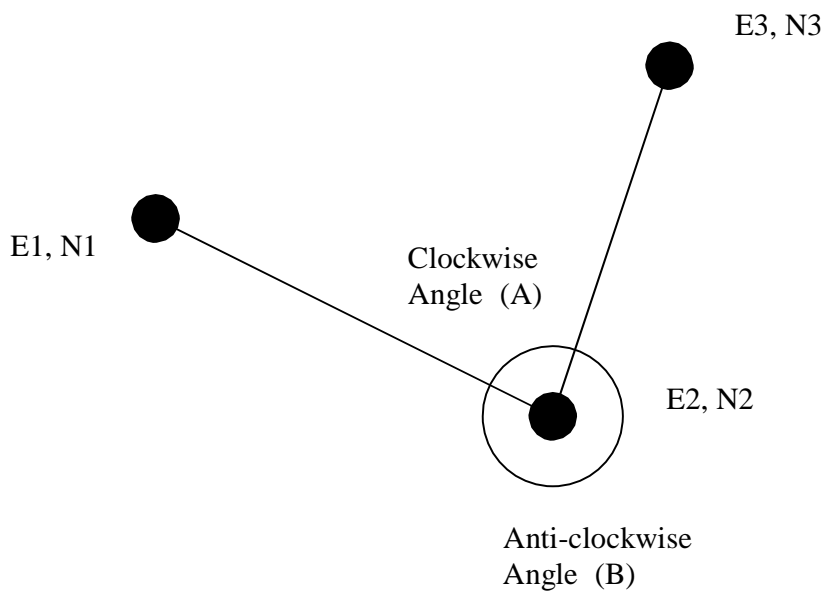
Diameter: D

## ANGLE

### Introduction

Calculates the clockwise and anti-clockwise angles between 3 known points.

### Diagram



### Input

Co-ordinates of 3 nodes: (E1, N1) (E2, N2) (E3, N3)

### Output

Clockwise angle: A  
Anti-clockwise angle: B

### **Note:**

**The output results are clockwise and anti-clockwise angles, NOT necessarily internal or external angles.**

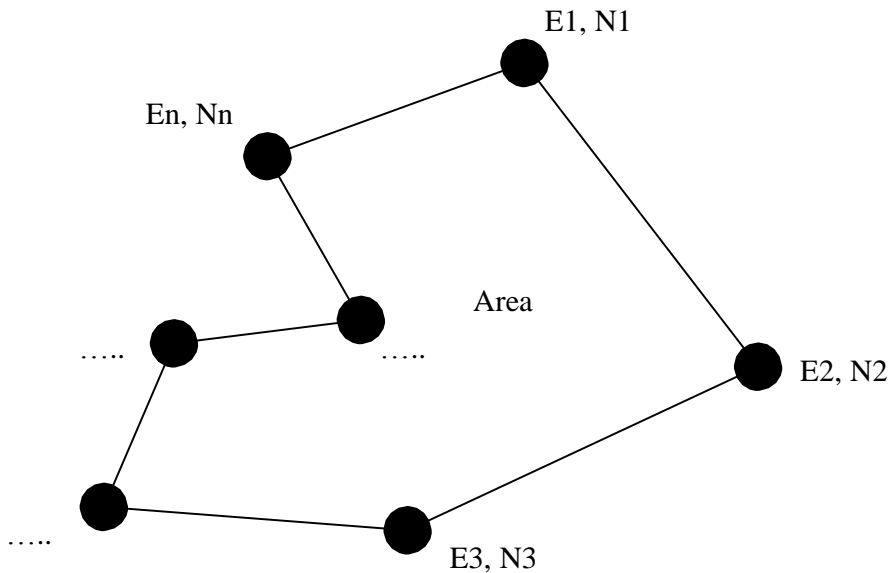
## AREA

### Introduction

Calculates the area of an enclosed polygon given the co-ordinates of any number of nodes.

Note: The polygon is closed by re-entering the first co-ordinate at the end of the loop.

### Diagram



### Input

Co-ordinates of nodes: (E1, N1) (E2, N2) (E3, N3) ..... (En, Nn) (E1 N1)

### Output

No of Nodes: n  
Total enclosed area: Area

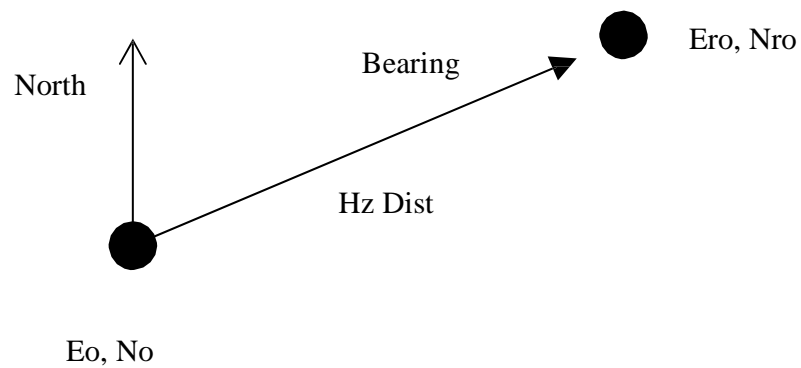
## BRG~DIST

### Introduction

Calculates the whole circle azimuth and distance between two known points.

Co-ordinates are entered from Station to RO.

### Diagram



### Input

Station Co-ordinates: (Eo, No)  
Reference Object Co-ordinates: (Ero, Nro)

### Output

Bearing: Bearing  
Hz Distance: Hz Dist

## CIRCLE

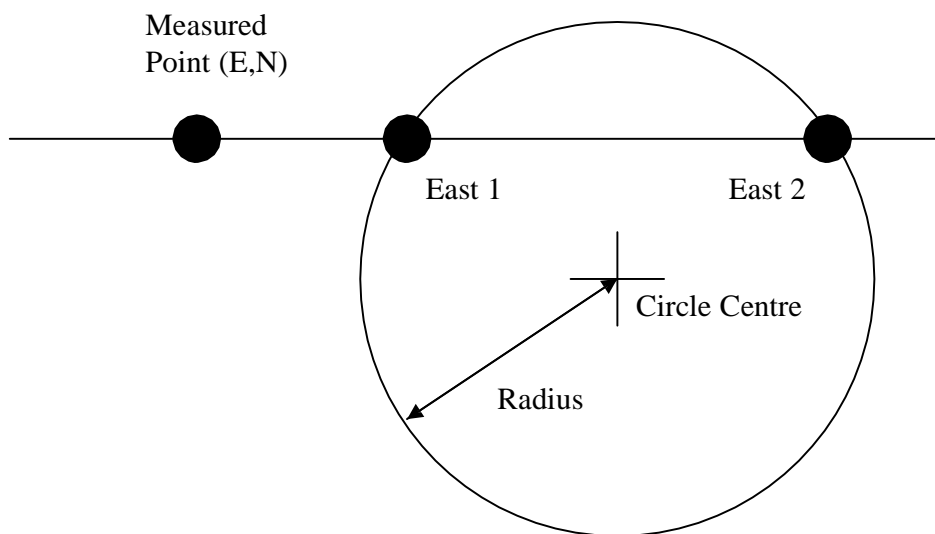
### Introduction

This program calculates two ordinate values of a circle, given another ordinate. ie: Given a Northing which passes through any given circle, the program will calculate two Easting values that the circle crosses.

This program has been used for setting-out curved edge-trim where the centre of radius is outside of the building.

If the given ordinate does not pass through the circle; a message is displayed.

### Diagram



### Input

Circle Centre: (E, N)  
Circle Radius: R  
Ordinate: E or N

### Output

Circle crossing ordinates: N or E

## COLUMN

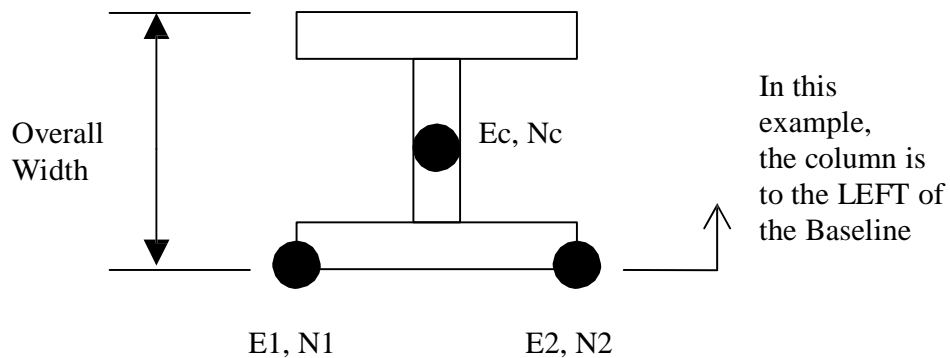
### Introduction

Determines the centre of a column given the co-ordinates of two adjacent corners and the overall width of the column section.

The column direction from the baseline must be given as “to the left” or “to the right”.

A check is also made to determine the squareness of the observations/column.

### Diagram



### Input

Two corner co-ordinates: (E1, N1) (E2, N2)  
Overall Column Width: Width

### Output

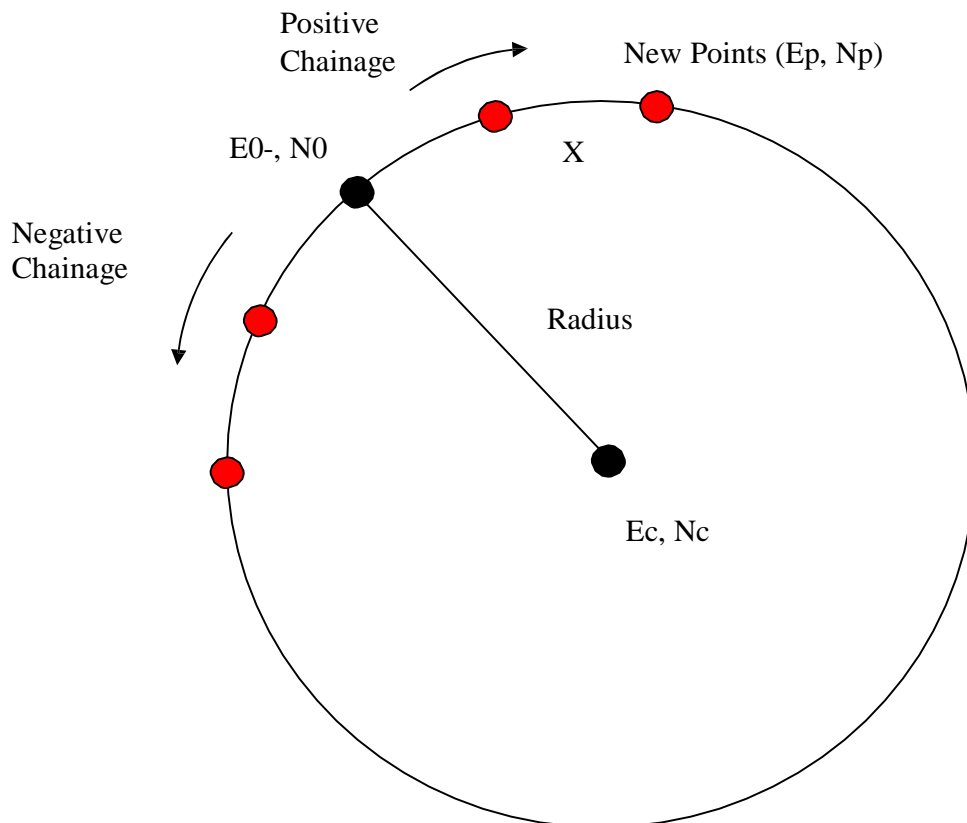
Squareness: S  
Column Centre Co-ordinates: (Ec, Nc)

## CURVE

### Introduction

Determines the setting-out co-ordinates of points on a curve.

### Diagram



### Input

Circle Centre:  $(E_c, N_c)$   
Starting Point:  $(E_0, N_0)$   
+'ve or -'ve Chainage:  $X$

### Output

Radius:  $R$   
Curve Points:  $(E_p, N_p)$

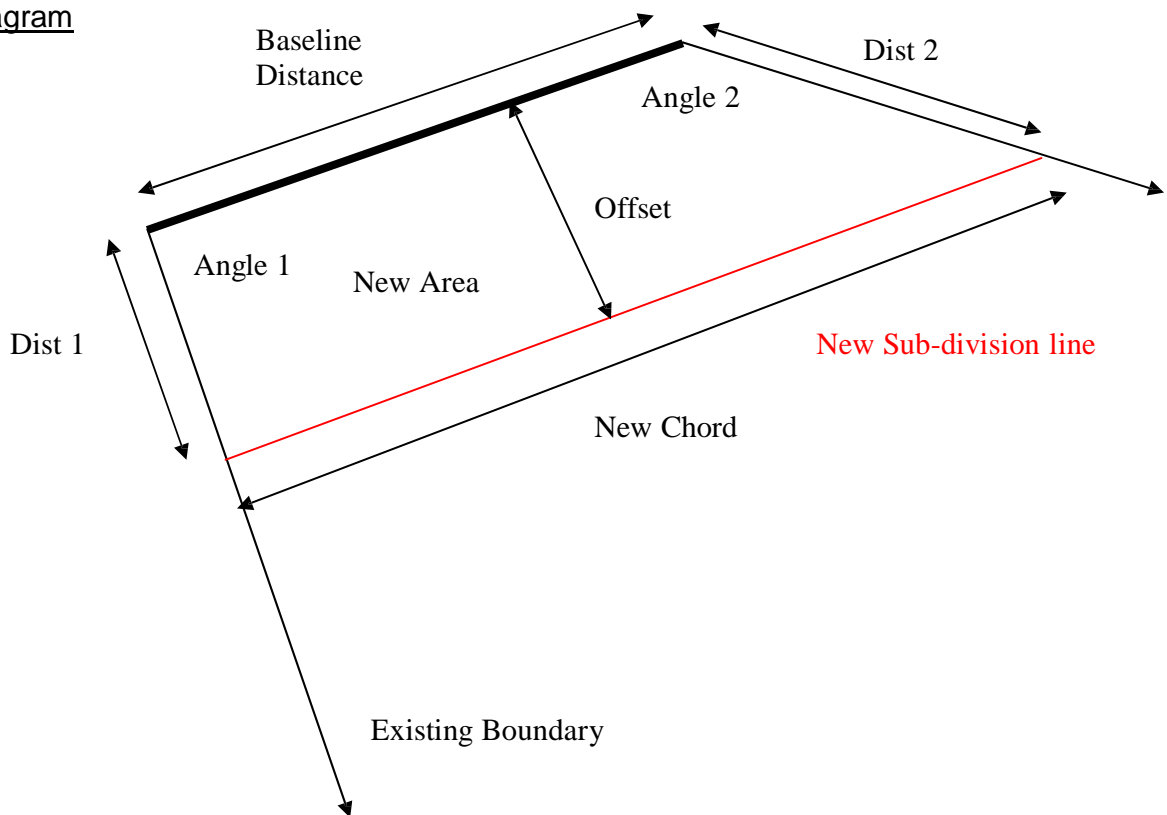
## CUT~AREA

### Introduction

Determines the location of a cut-line for the sub-division of a Plot into a known area. New sub-division line is parallel to existing boundary.

**Note:** Angles may be internal or external and in any order. Example shown only.

### Diagram



### Input

Baseline Distance:	Distance
Required Area (m <sup>2</sup> ):	New Area
Angles 1 & 2:	$\theta_1$ & $\theta_2$

### Output

Distance along adjacent legs:	D1 & D2 (in same order as angles were input)
Offset distance:	Offset
Cross plot "Chord" distance:	Chord Distance



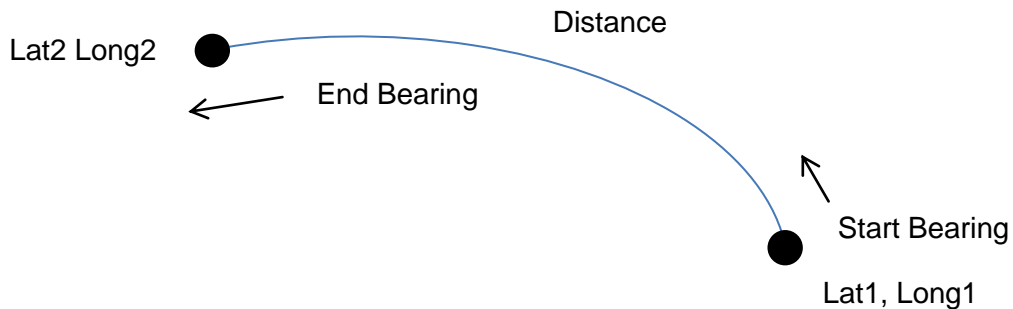
## HAVERSIN

### Introduction (Haversine Formula)

Calculates the Start & End bearings between 2 points on the Earth's surface. It also calculates the surface distance between them (in miles and kilometres).

*The shortest distance between 2 points follows the line of a "Great Circle" and the bearing is constantly changing throughout the journey.*

### Diagram



### Input

Co-ordinates of 2 known points: (Latitude1, Longitude1) & (Latitude2, Longitude2)

**Note:** Geographical positions are given relative to the Greenwich meridian and Equator.

### Output

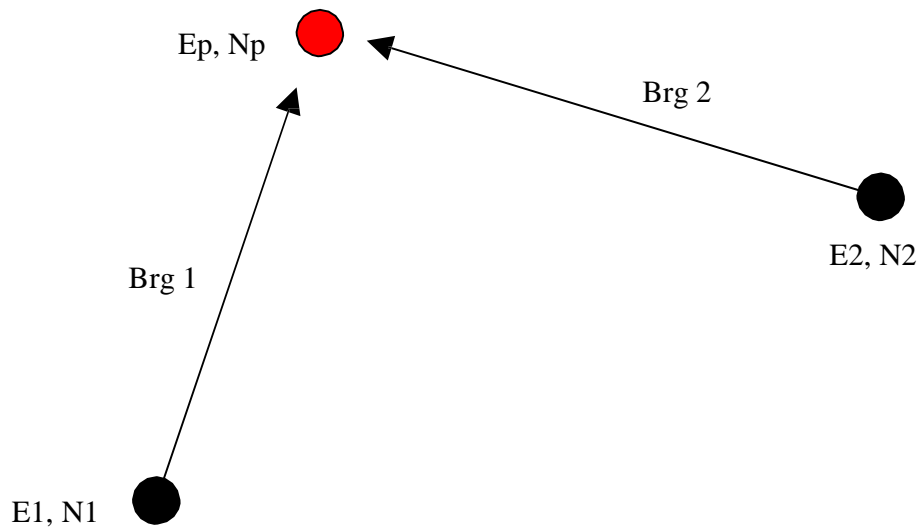
Start & Finish bearings: Start, End  
Distance: Miles & Kilometres

## INT~BEAR

### Introduction

This program calculates the 2-D co-ordinates of an unknown point given the co-ordinates of two known points and two intersecting bearings from them.

### Diagram



### Input

Known Stations:                     $(E_1, N_1)$   $(E_2, N_2)$   
Bearings:                            Bearing 1 & Bearing 2

### Output

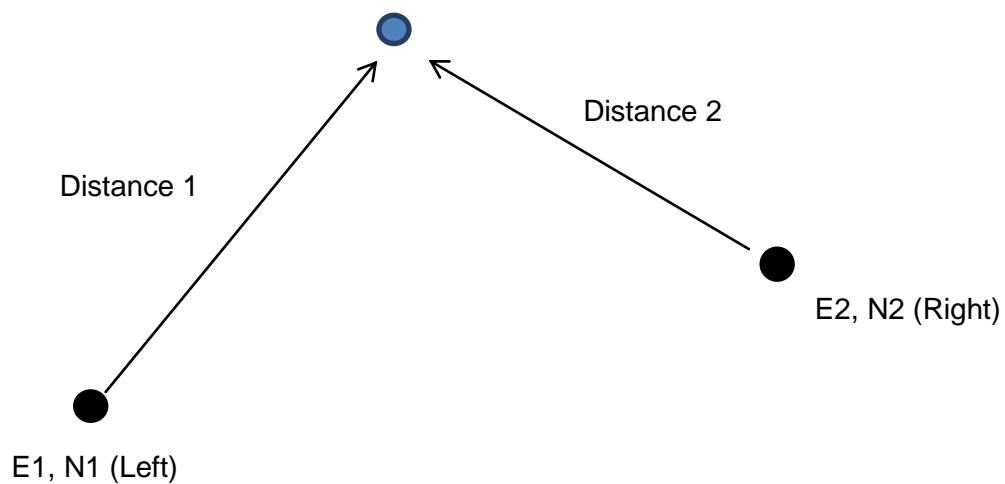
Intersection co-ordinates:        $(E_p, N_p)$

## INT~DIST

### Introduction

Calculates the co-ordinates of a point, given 2 distances from 2 known points. Since there are two possible solutions, care must be taken to distinguish between the “left” and “right” stations.

### Diagram



### Input

Co-ordinates of 2 known points: (E1, N1) & (E2, N2)  
Distance from each station: D1 & D2

### Output

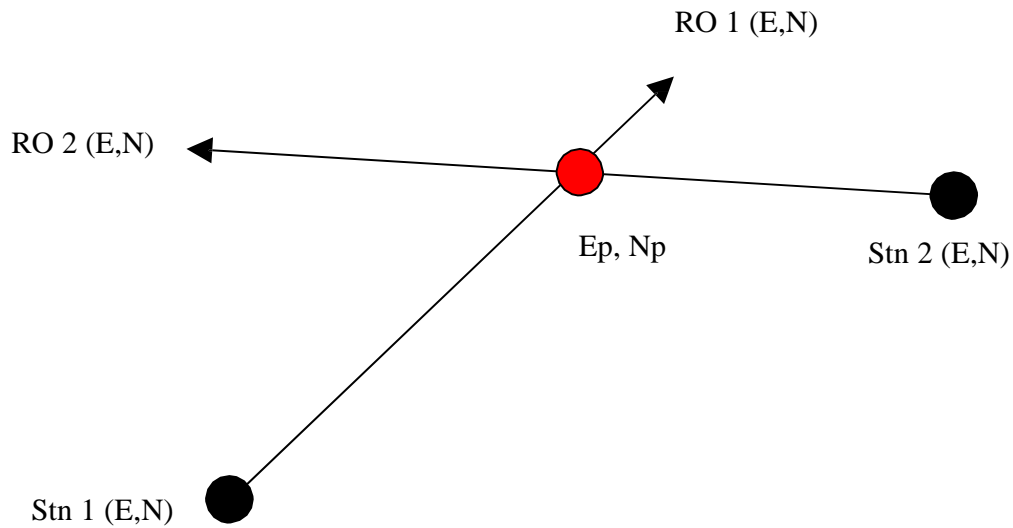
Co-ordinates of unknown point: E3, N3

## INT~LINE

### Introduction

This program calculates the 2-D co-ordinates of an unknown point from the intersecting lines between two sets of 2 points.

### Diagram



### Input

Known Stations:  $Stn\ 1\ \&\ Stn\ 2\ (E, N)$

Known Reference Points:  $RO\ 1\ \&\ RO\ 2\ (E, N)$

### Output

Intersection co-ordinates:  $(E_p, N_p)$

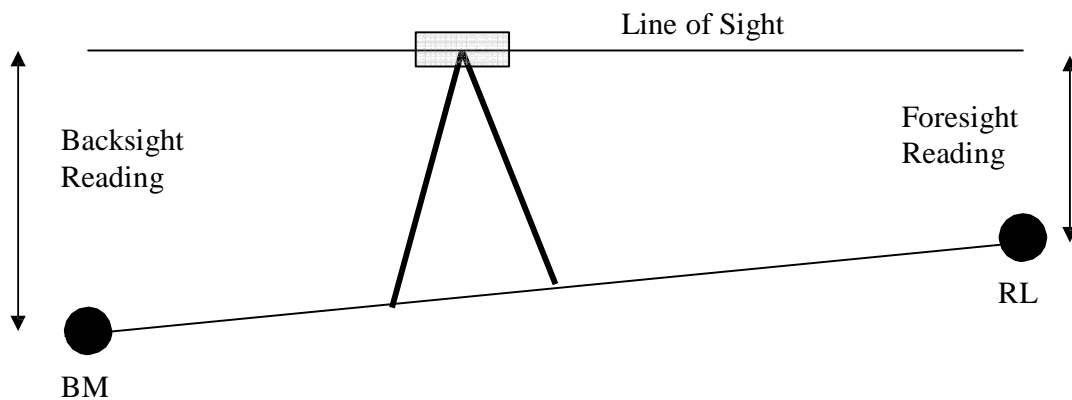
## LEVELS/LEVELING

### Introduction

Computes the reduced level of any number of points using ordinary levelling techniques. FX7400G=Single set-up only. \*\* FX9860GII also allows combination of back/foresights to reduce a level run.

**No adjustment is applied.**

### Diagram



### Input

Benchmark Value:	BM
Backsight Reading:	BS
Intersight Readings:	IS1, IS2, IS3...
** Foresight Readings:	FS

### Output

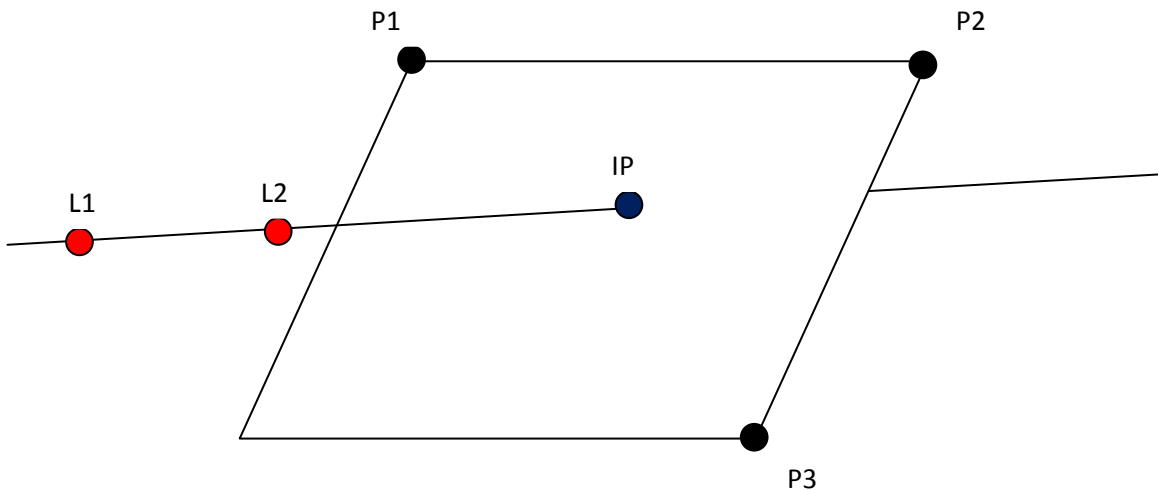
Reduced Levels:	RL1, RL2, RL3...
-----------------	------------------

## LN2PLANE

### Introduction

This program calculates the intersection co-ordinates of a Line to a Plane.  
This is useful where a hidden point is required and it is not possible to measure a distance to the point or whereby defining the plane, the distance is no longer required.

### Diagram



### Input

Plane co-ordinates:  $(Px1, Py1, Pz1)$ ,  $(Px2, Py2, Pz2)$ ,  $(Px3, Py3, Pz3)$

Line co-ordinates:  $(Lx1, Ly1, Lz1)$ ,  $(Lx2, Ly2, Lz2)$

### Output

Intersection co-ordinates:  $(IPx, IPy, IPz)$

3D Distances: L1 to L2 & L2 to IP

Note:

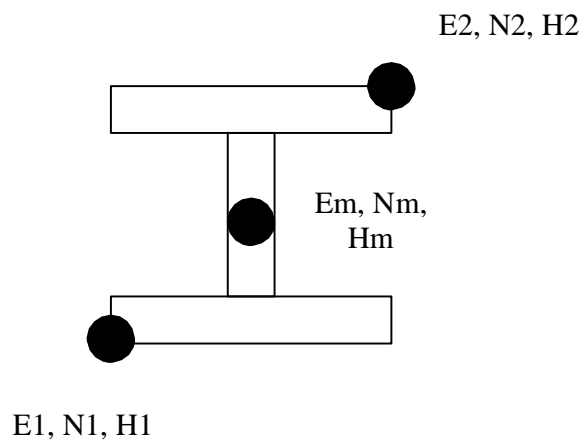
1. The order (and position) of L1 & L2 is not critical as the defined Line is infinite in length.  
ie The points may be either side of the Plane.
2. The distances L1-L2 & L2-IP are always shown as POSITIVE.

## MEAN~XYZ

### Introduction

Calculates the mean of two co-ordinates. eg. Two diagonal column corners.  
(Option to calculate 3D mean if necessary – otherwise enter zeros)

### Diagram



### Input

Two co-ordinates: (E1, N1, H1) (E2, N2, H2)

### Output

Mean co-ordinate: (Em, Nm, Hm)

## NOTEBOOK

### Introduction

Stores up to 9 numeric values when a pen and paper aren't available.

### Input

Numeric values: N1, N2, N3.....N9

### Output

Numeric values: N1, N2, N3.....N9

**Note: The values may be overwritten/changed when another program is used. This program should only be used for temporary storage only.**



## OFFSET

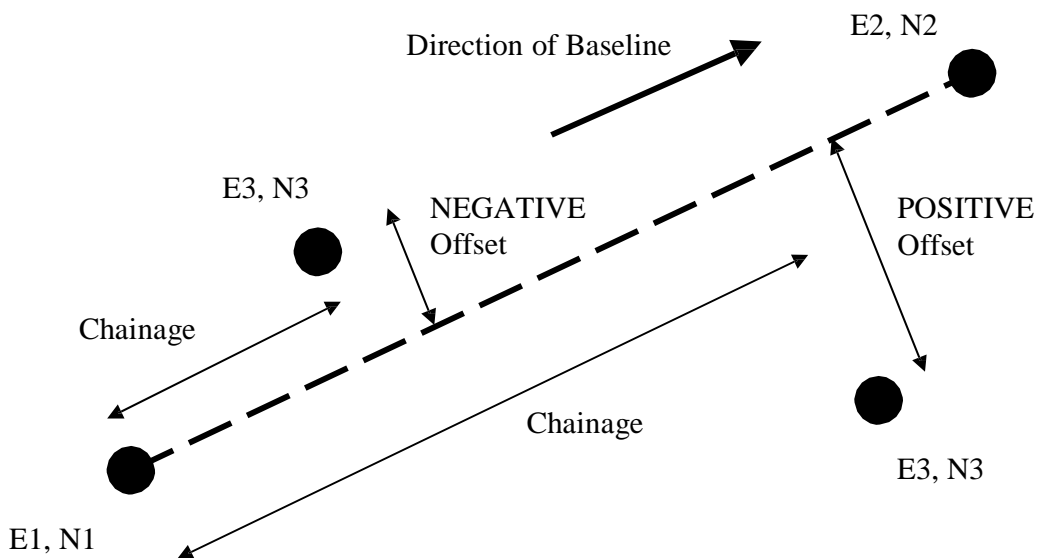
### Introduction

This program calculates the perpendicular distance (offset) of a point from a given baseline, as well as the distance along the baseline to that perpendicular intersection (chainage).

Positive offsets are to the RIGHT of the line and negative offsets are to the LEFT of the line.

Note: Chainages can also be negative.

### Diagram



### Input

Baseline co-ordinates: (E1, N1) (E2, N2)  
Other points: (E3, N3)

### Output

Offset: +/- Offset  
Chainage: Chainage

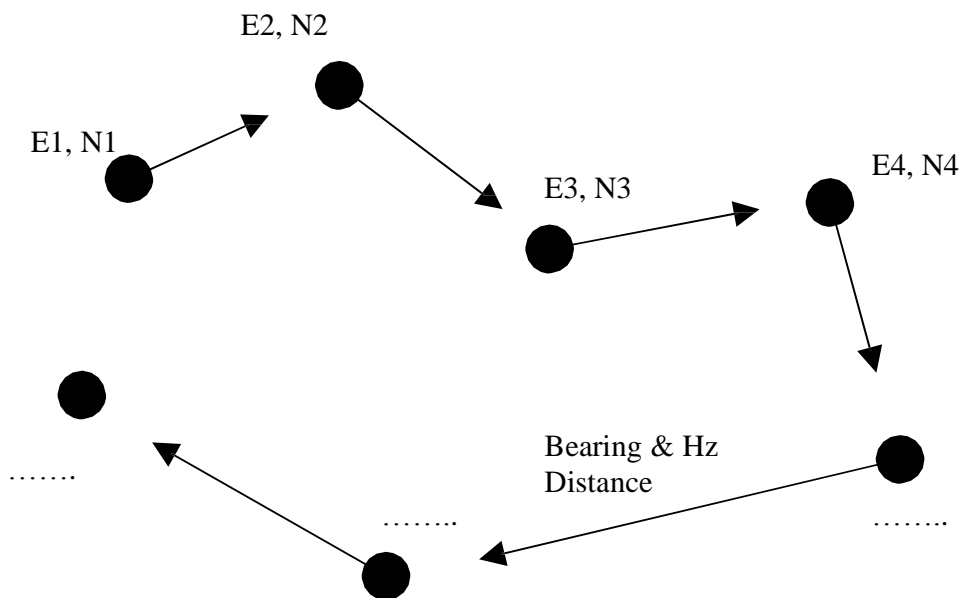
## POLYGON

### Introduction

Computes the “Bearing and Distances” between points in a series. eg Traverse.

The input of the data is quicker as each co-ordinate is entered only once.

### Diagram



### Input

Co-ordinates: (E1, N1) (E2, N2) (E3, N3) ..... (En, Nn)

### Output

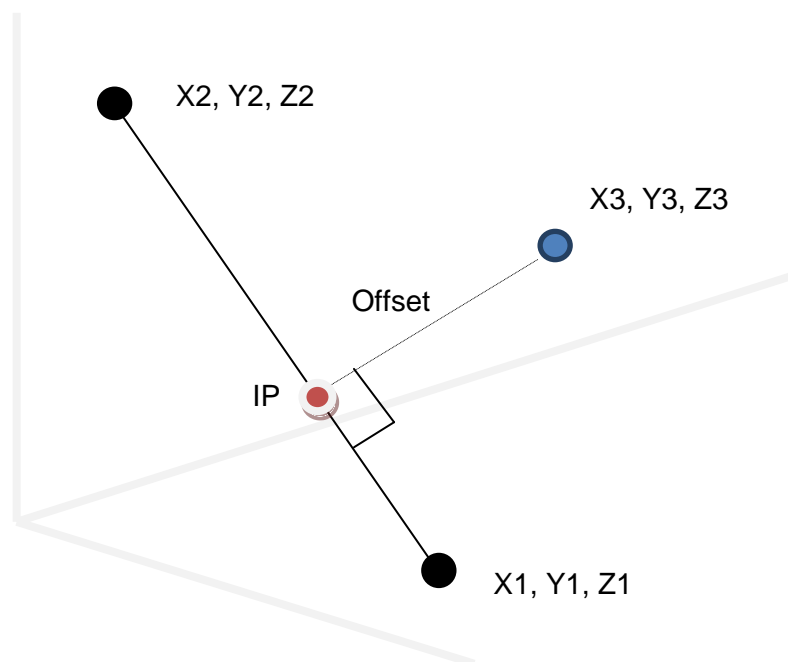
Bearing & Distances: (E1, N1) to (E2, N2)  
(E2, N2) to (E3, N3)  
(E3, N3) to ...

## PT2PLINE

### Introduction

This program calculates the perpendicular distance from a point to a 3D line defined by 2 points. Also calculates the co-ordinates of the intersection point.

### Diagram



### Input

2 points defining 3D line:  $(X_1, Y_1, Z_1)$  &  $(X_2, Y_2, Z_2)$   
Survey point:  $(X_3, Y_3, Z_3)$

### Output

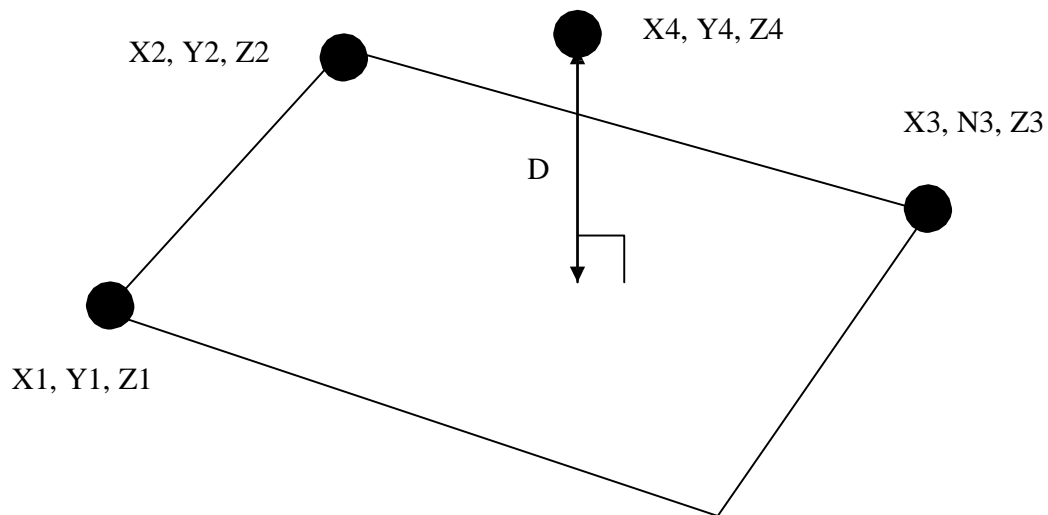
Co-ordinates of Intersected Point:  $(IP_x, IP_y, IP_z)$   
Perpendicular offset to line: Offset

## PT2PLANE

### Introduction

This program calculates the perpendicular distance from a surveyed point to a known inclined plane (defined by 3 points). May be used to calculate non-flatness of a surface by defining 3 corners.

### Diagram



### Input

Plane co-ordinates:  $(X_1, Y_1, Z_1)$   $(X_2, Y_2, Z_2)$   $(X_3, Y_3, Z_3)$

Other points:  $(X_4, Y_4, Z_4)$

### Output

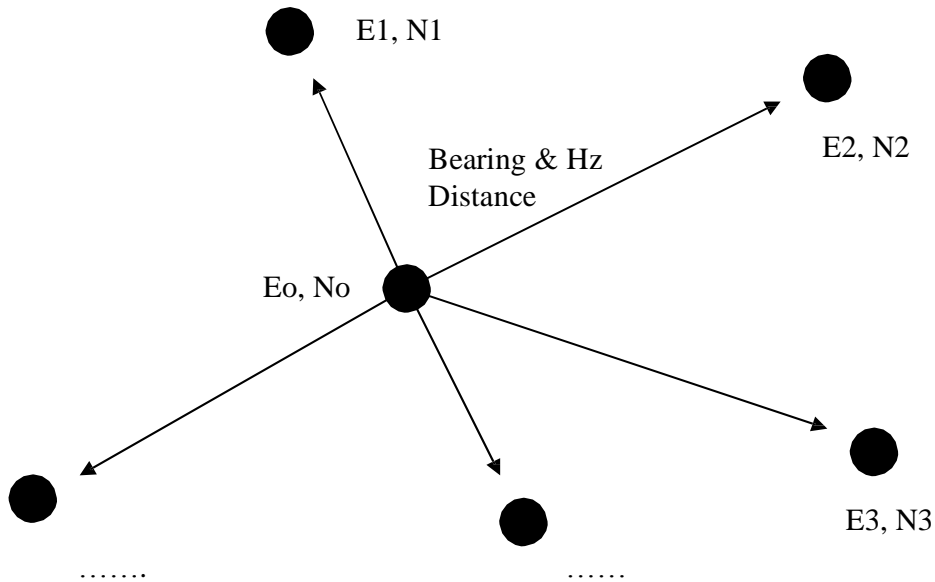
Perpendicular distance:  $D$

## RADIAL

### Introduction

Computes the “Bearing & Distances” from a central point to any number of other points. This program removes the need to keep re-entering the first set of co-ordinates.

### Diagram



### Input

“From” co-ordinates:

$(E_o, N_o)$

“To” co-ordinates:

$(E_1, N_1)$   $(E_2, N_2)$   $(E_3, N_3)$  .....

### Output

Bearing & Distances:

$(E_o, N_o)$  to  $(E_1, N_1)$

$(E_o, N_o)$  to  $(E_2, N_2)$

$(E_o, N_o)$  to  $(E_3, N_3)$  .....

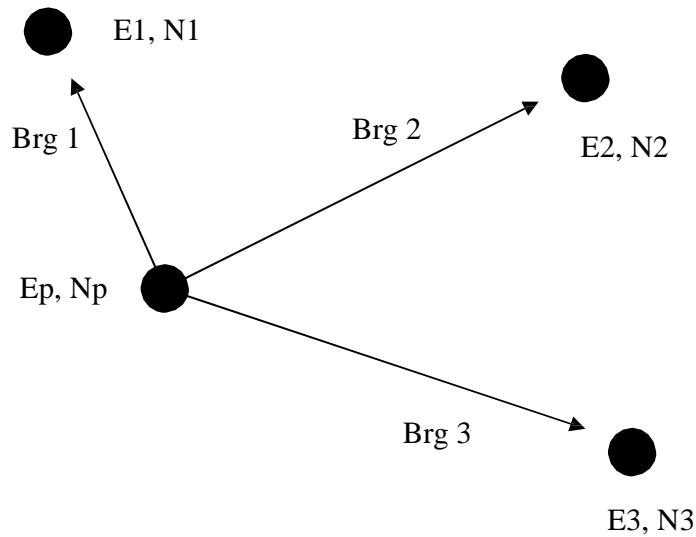
## RESECT

### Introduction

Computes the co-ordinates of an Instrument Station by observing three arbitrary bearings to three known points.

**NOTE: The co-ordinates of the known stations must be entered and observed in a CLOCKWISE order.**

### Diagram



### Input

Known co-ordinates:       $(E_1, N_1)$   $(E_2, N_2)$   $(E_3, N_3)$   
Arbitrary Bearings:       $Brg_1$   $Brg_2$   $Brg_3$

### Output

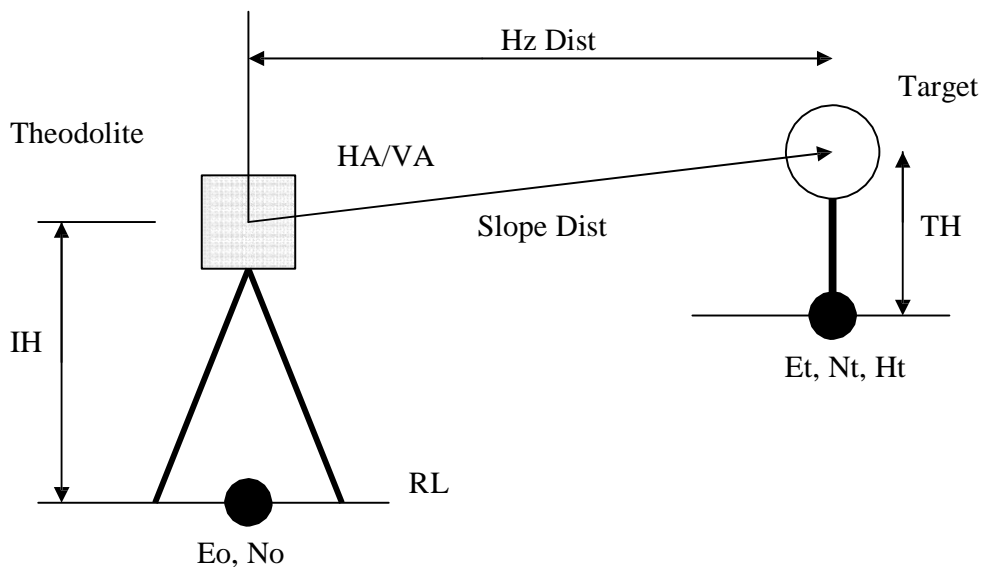
Resected co-ordinates:     $(E_p, N_p)$

## SURVEY

### Introduction

Reduces measured angles and distances to a target into X, Y, Z co-ordinates

### Diagram



### Input

Station Co-ordinates:	(Eo, No)
Station Reduced Level:	RL
Instrument Height:	IH
Known Bearing or RO Coords:	Bearing or (Ero, Nro)
Horizontal Angle:	Hz Ang
Vertical Angle:	VA
Slope or Hz Distance:	Slope or Hz Dist
Target Height:	TH

### Output

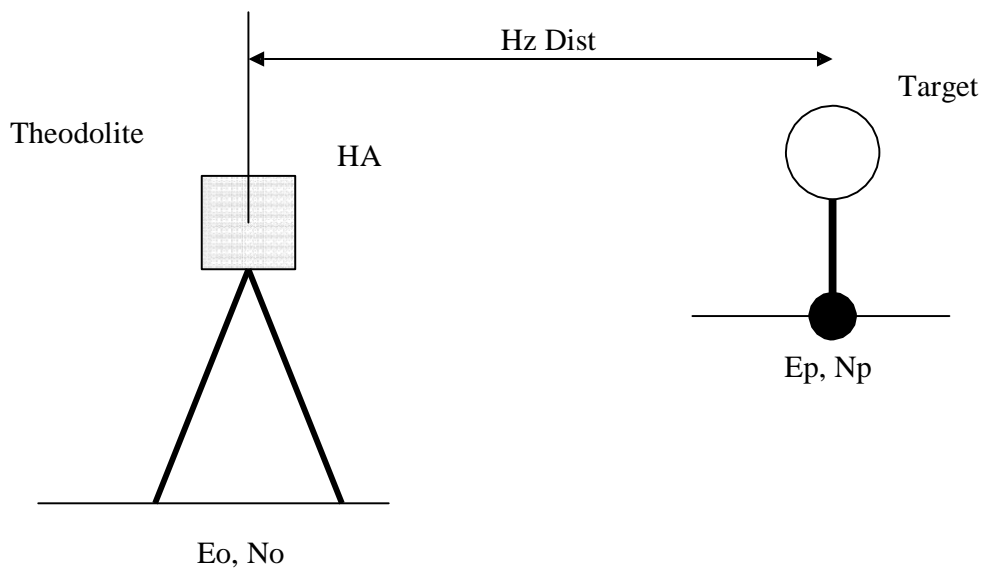
Target Co-ordinates:	(Et, Nt, Ht)
Hz Dist:	Hz Dist

## SURVEY2D

### Introduction

Simplified survey reduction program. Reduces 2D measured angles and distances to a target into X & Y co-ordinates.

### Diagram



### Input

Station Co-ordinates:	( $E_o, N_o$ )
Known Bearing or RO Coords:	Bearing or ( $E_{ro}, N_{ro}$ )
Horizontal Angle:	Hz Ang
Hz Distance:	Hz Dist

### Output

Target Co-ordinates:	( $E_p, N_p$ )
----------------------	----------------



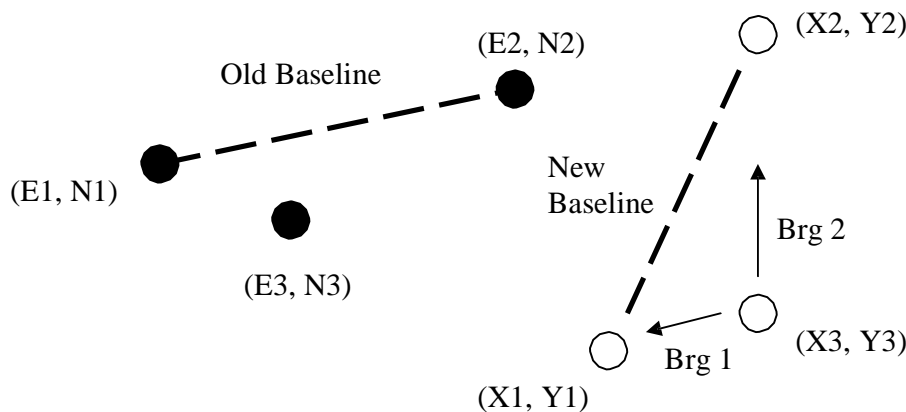
## TRANSFRM

### Introduction

This program uses two known points to transform any other points between two different co-ordinate systems. A baseline is used to calculate the Scale, Rotation and Translation parameters between the systems.

Calculates the new bearings to the new baseline in case this point is required as an instrument set-up.

### Diagram



### Input

Original co-ordinates:	(E1, N1) (E2, N2)
New co-ordinates:	(X1, Y1) (X2, Y2)
Other points:	(E3, N3) (E4, N4) (E5, N5) .....

### Output

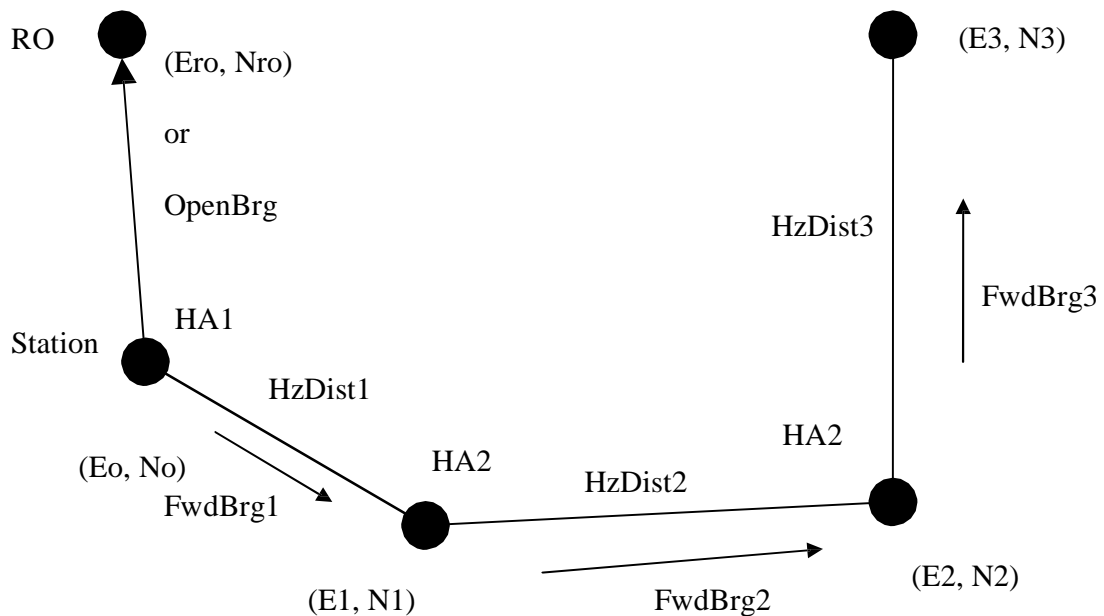
Original Baseline Distance:	Old Baseline
New Baseline Distance:	New Baseline
Scale Factor:	SF
Scale Error per Km:	Error/Km
Transformed Points:	(X3, Y3) (X4, Y4) (X5, Y5) .....
Bearings to Basepoints:	Brg 1, Brg 2

## TRAVERSE

### Introduction

Computes station co-ordinates of a traverse given a starting baseline and a series of measured horizontal angles and forward distances. The traverse may be left open or closed.

### Diagram



### Input

Station co-ordinates:	(Eo, No)
RO co-ords or Opening Bearing:	(Ero, Nro) or OpenBrg
Measured Angles:	HA1, HA2, HA3.....
Measured Horz Distances:	HzDist1, HzDist2, HzDist3.....

### Output

Forward Bearings:	FwdBrg1, FwdBrg2, FwdBrg3.....
Intermediate co-ordinates:	(E1, N1), (E2, N2), (E3, N3)....

## UNI~COLS

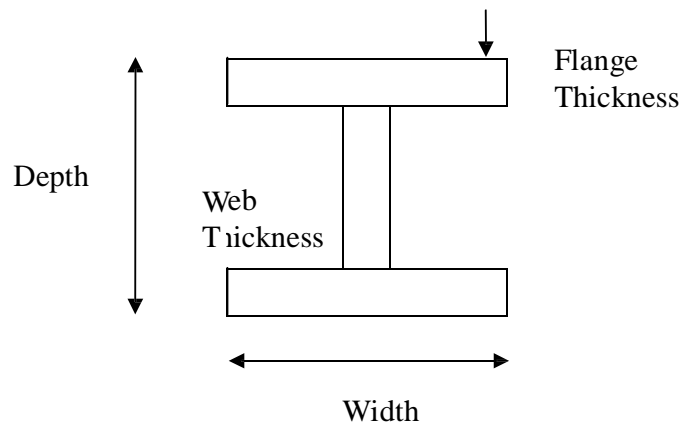
### Introduction

Gives the Width/Depth and Flange/Web thicknesses of 31 no. Standard Universal Columns.

**Designation must be 3 numbers separated by x (multiplier) symbol.**

Also allows you to view the Designations of all 31 no. columns.

### Diagram



### Input

UC Designation:            AAxBBxCC

### Output

Column Dimensions:        Depth, Width, Flange, Web

## VECTORS

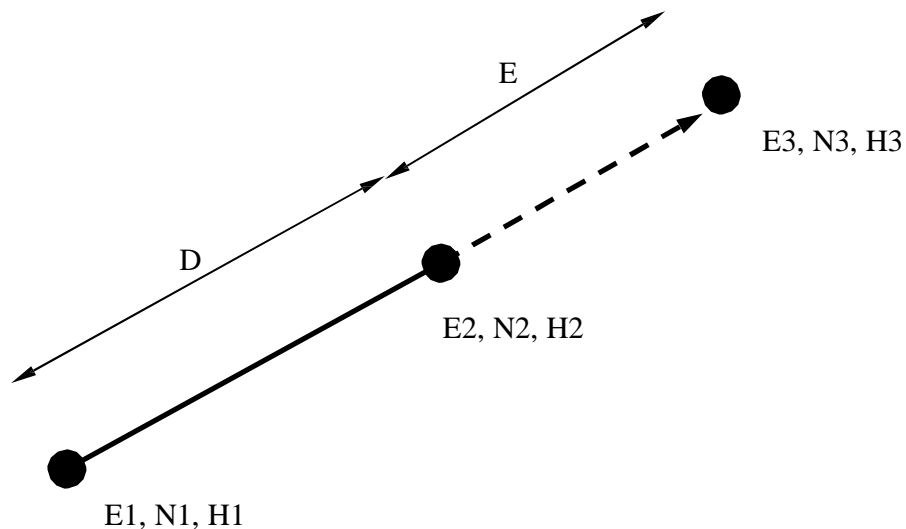
### Introduction

Creates a 3-D point in space at a specified further distance along a line defined by two 3-D points. This is useful to co-ordinate a point that is not visible. The program is 2-D if the heights of the two points are the same.

The distance between the two known points is also computed so that a check may be made if the distance is known.

The vector may be extended negatively as well as positively from the second point.

### Diagram



### Input

2 known points:           (E1, N1, H1) (E2, N2, H2)  
Extension of vector:       E

### Output

Extended point:           (E3, N3, H3)  
Distance between 1-2:     D

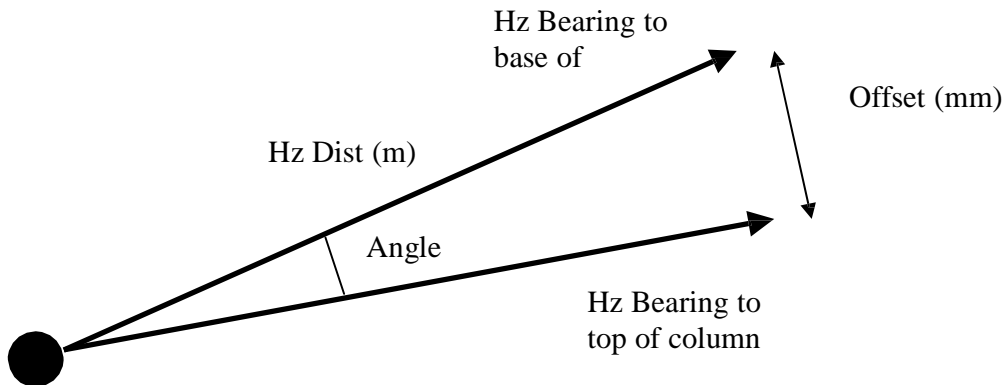
## VERTICAL

### Introduction

This program calculates the offset of a point given a difference in angle and a distance to the point. This is used to determine the verticality of a column by measuring the difference in horizontal angle at the top to the base and by measuring the horizontal distance to the column.

Since small angles are usually involved, the angle is made up of “minutes” and “seconds” only.

### Diagram



### Input

Angle:                    min, sec  
Distance:                m

### Output

Offset:                    mm

### EXAMPLES

The following examples indicate how the programs can be used.

#### 1PT~CFIX

**Q:** From an instrument set-up at (123.456mE, 234.567mN), the following horizontal angles were measured to the left and right hand sides of a tubular column respectively:  $246^{\circ}13'57''$  and  $247^{\circ}54'32''$ . In addition, a horizontal distance of 13.579m was measured to the column at the mid-point of these angles. Calculate the centre co-ordinates and the radius.

**A:** (110.764mE, 229.198mN) and 0.202m.

#### 2PT~CFIX

**Q:** Two points were measured on the surface of a circular column. The column is to the LEFT of the points looking from the first to the second.

The radius of the column is known to be 0.406m.

Calculate the centre co-ordinates of the column.

Point	Easting	Northing
1	23.432m	78.234m
2	23.823m	78.765m

**A:** (23.437mE, 78.640mN).

#### 3D~CFIX

**Q:** Calculate the centre co-ordinates and radius of a 3D (inclined) circle with the following points on its perimeter.

Point	Easting	Northing	Height
1	80.779m	90.198m	23.567m
2	78.334m	66.990m	25.567m
3	45.345m	67.623m	34.123m

**A:** (61.890mE, 80.840mN, 29.037mH) and radius 21.778m.

3D~DIST

**Q:** Calculate the slope distance between the following surveyed points:

Point	Easting	Northing	Elevation
1	648.851m	885.314m	4.105m
2	650.056m	885.527m	3.756m

**A:** 1.272m

3PT~CFIX

**Q:** The following co-ordinates were measured around the edge of a circle. Calculate the centre co-ordinates and the diameter.

Point	Easting	Northing
1	23.432m	78.234m
2	45.323m	98.765m
3	67.334m	66.999m

**A:** (46.217mE, 75.876mN) and 45.814m.

ANGLE

**Q:** Calculate the clockwise and anti-clockwise angles between the following 3 points. (Point 2 is at the apex).

Point	Easting	Northing
1	80.779m	90.198m
2	78.334m	66.990m
3	45.345m	67.623m

**A:**  $265^{\circ}05'06.9''$  &  $94^{\circ}54'53.1''$

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AREA

**Q:** The corners of a field have the following co-ordinates. What is the total area?

Point	Easting	Northing
1	45.345m	67.623m
2	78.334m	66.990m
3	80.779m	90.198m
4	66.678m	96,786m
5	35.121m	88.009m

Hint: The co-ordinates of the first point must be re-entered at the end to close the loop.

**A:** 1025.991m<sup>2</sup>

BRG~DIST

**Q:** Calculate the bearing and distance between the points (509.456mE, 234.656mN) and (661.443mE 423.565mN).

**A:** 38° 49' 06.48" and 242.4596m.

CIRCLE

**Q:** Calculate the Eastings of a circle with centre (108.510mE, 254.523mN) and radius 25m, at a Northing of 250.000mN

**A:** 133.097mE and 83.923mE

COLUMN

**Q:** The co-ordinates of 2 corners of a column were measured as (345.567mE, 256.323mN) and (345.867mE, 256.325mN). If the column measures 0.355m to the left of these points, calculate the column centre.

**A:** (345.716mE, 256.501mN).



### CURVE

**Q:** Determine the next 3 points clockwise around a curve at 3m arc distances, on a circle with centre 104.567mE, 345.345mN and with a starting point of 112.879mE, 366.909mN.

**A:** (115.600mE, 365.652mN), (118.136mE, 364.053mN) & (120.444mE, 362.139mN).

### CUT~AREA

**Q:** A new plot boundary is required parallel to an existing boundary which is 135.978m long, with angles of 103° and 129° at either end. The new area should be 6800m<sup>2</sup>. At what parallel offset should the new boundary be placed.

**A:** 42.949m.

### HAVERSIN

**Q:** Calculate the distance from Windsor Castle (Lat N51° 29' 00", Long W0° 36' 16") to the St Paul's Cathedral (Lat N51° 30' 50", Long W0° 5' 53")

Hint: West is entered as NEGATIVE in calculator. eg -0°36°16°

**A:** 35.2km or 21.9miles

### INT~BEAR

**Q:** The bearings from 2 independent stations: (234.657mE, 544.109mN) and (566.855mE, 607.233mN) were 56° 12' 23" and 294° 56' 54" respectively. Calculate the co-ordinates of the intersected point.

**A:** (426.519mE, 672.519mN)

INT~DIST

**Q:** Two distances are measured from 2 known points.

Point	Easting	Northing
Left	45.345m	67.623m
Right	78.334m	66.990m

Distances of 15.600m & 34.109m are measured from the Left and Right points respectively. Calculate the co-ordinates of the unknown point.

**A:** (48.195mE, 82.960mN)

INT~LINE

**Q:** Calculate the co-ordinates of a point lying on the intersection of 2 lines between the following points:

Line 1 – (234.456mE, 432.654mN) to (342.564mE, 324.465mN)

Line 2 – (789.123mE, 687.109mN) to (987.321mE, 897.091mN)

**A:** (396.183mE, 270.806mN)

LEVELS

**Q:** A Benchmark with a value of 18.550m, was used for a Backsight reading of 1.710m. Calculate the reduced levels of Intersight Points with readings of 1.347m, 1.365m and 1.450m.

**A:** 18.913mH, 18.895mH and 18.810mH

LN2PLANE

**Q:** The co-ordinates of 3 points on an inclined concrete wall are: (10.123, 10.456, 5.678), (5.515, 8.939, 2.010) & (7.777, 9.999, 8.888) and two 3D points on a line towards the wall are (1.001, 2.002, -0.910) & (5.543, -3.712, 4.190). What are co-ordinates of the intersection of the line and the wall and the distance from the second “line” point to the wall?

**A:** (-2.416, 6.301, -4.747) and 15.603m

MEAN~XYZ

**Q:** Calculate the centre co-ordinates of a column given the co-ordinates of two diagonal corners of (233.434mE, 344.544mN, 12.546mH) and (233.826mE, 344.200mN, 14.546mH).

**A:** (233.630mE, 344.372mN, 13.546mH)

NOTEBOOK

No calculations are performed in this program.

OFFSET

**Q:** From a Baseline with end co-ordinates of (109.901mE, 227.810mN) and (110.768mE, 320.912mN), calculate the Offset and Chainage of a measured point at (110.345mE, 270.508mN).

**A:** 0.046 (to the right) and 42.700m (along the line).

POLYGON

**Q:** Calculate the bearings and distances between the following points:

Point	Easting	Northing
1	23.432m	78.234m
2	45.323m	98.765m
3	67.334m	66.999m
4	66.678m	96,786m

**A:** 1 to 2:  $46^{\circ}50' 10.35''$  & 30.0123m, 2 to 3:  $145^{\circ} 16' 53.4''$  & 38.6466m, 3 to 4:  $358^{\circ} 44' 18''$  & 29.7942m.

PT2LINE

**Q:** Calculate the distance of a point (12.276mE, 56.143mN, 9.444mH) to a line defined by the following points:

Point	Easting	Northing	Level
1	19.425m	50.002m	7.891m
2	9.120m	54.187m	10.877m

**A:** 3.109m

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PT2PLANE

**Q:** A sloping concrete surface has the following co-ordinates at three of its corners, calculate how high the surveyed point is from this surface:

Point	Easting	Northing	Elevation
1	648.851m	885.314m	4.105m
2	650.056m	885.527m	3.756m
3	649.298m	886.012m	3.756m

Surveyed point on concrete: 650.170mE, 885.734mN, 3.638mH

**A:** 17mm.

RADIAL

**Q:** Calculate the bearings and distances from Station 1 at co-ordinates (45.678mE, 23.519mN) to the following points:

Point	Easting	Northing
2	23.432m	78.234m
3	45.323m	98.765m
4	67.334m	66.999m.

**A:** Station 1 to 2:  $337^{\circ}52'27''$  & 59.0645m, Station 1 to 3:  $359^{\circ}43'46''$  & 75.2468m, Station 1 to 4:  $26^{\circ}28'35.15''$  & 48.5746m

RESECT

**Q:** Calculate the free-station co-ordinates of an instrument observing to the following points (listed in clockwise order):

Point	Easting	Northing
1	1123.457m	345.675m
2	987.650m	157,913m
3	246.810m	213.546m

to which the following arbitrary Horz Angles were observed:

$00^{\circ}50'53''$ ,  $18^{\circ}55'58''$  and  $197^{\circ}03'44''$  respectively.

**A:** (500.0128mE, 200.0001mN)

SURVEY

**Q:** The following information was recorded from an instrument. Use the data to co-ordinate the target. Station co-ordinates: (502.405mE, 789.765mN). Station Reduced Level: 18.900mH. Instrument Height above Station: 1.612m. RO co-ordinates: (578.324mE, 340.822mN). Horz Angle:  $233^{\circ}44'55''$ . VA:  $88^{\circ}33'22''$ . Slope distance: 45.543m. Target Height: 0.500m.

**A:** (534.1176mE, 822.4324mN, 21.1596mH)

SURVEY2D

**Q:** The following information was recorded from an instrument. Use the data to co-ordinate the target. Station co-ordinates: (502.405mE, 789.765mN). RO co-ordinates: (578.324mE, 340.822mN). Horz Angle:  $233^{\circ}44'55''$ . Horizontal distance: 45.543m.

**A:** (534.128mE, 822.443mN)

TRANSFRM

**Q:** 2 points were arbitrarily co-ordinated as (105.657mE, 194.004mN) and (95.574mE, 209.869mN), from an unknown station with arbitrary instrument co-ordinates of (100.000mE, 200.000mN).

If the two points were known and should have co-ordinates of (300.000mE, 500.000mN) and (318.800mE, 500.000mN) respectively, calculate the true instrument co-ordinates and the true bearing to the second observed point.

**A:** (308.0957mE, 501.5583mN) and  $98^{\circ}16'58.64''$ .

TRAVERSE

**Q:** From a known baseline of Station 1 (454.545mE, 767.676mN) and an RO with co-ordinates of (878.787mE, 232.323mN), the following Horz Angle and Horz Distance was measured to Station 2:  $45^{\circ}54'45''$  and 121.212m. After moving to this Station, an angle and distance of  $289^{\circ}08'23''$  and 34.434m was measured to Station 3. What are the co-ordinates of Station 3?

**A:** (407.9134mE, 662.9546mN)

UNI~COLS

**Q:** Obtain the Web and Flange thicknesses of a 254x254x89 UC.

**A:** 10.7mm and 17.3mm respectively.

VECTORS

**Q:** Two points have been co-ordinated as (723.884mE, 184.542mN, 18.567mH) and (732.676mE, 185.409mN, 18.689mH). Calculate the co-ordinates of a third point, if the slope distance from the second point to a third point is 3.075m.

**A:** (735.736mE, 185.711mN, 18.731mH)

VERTICAL

**Q:** The difference in the Horz Angle reading to a column edge from its base to the top is  $00^{\circ}01'48''$ . If the column is 12m away, calculate the plumb error of the column.

**A:** 6.3mm.

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for Casio fx-7400G & fx-9860GII

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**REVISIONS**

<u>Revision</u>	<u>Date</u>	<u>Updated</u>
1.0a	May 2003	Beta revision.
1.1	July 2003	“UC” program added.
1.2	April 2004	“2PT~CFIX” program added.
1.21	May 2004	“OFFSET” description corrected.
1.22	May 2004	“1PT~CFIX” program updated.
1.3	July 2005	“NOTEBOOK” program added.
1.4	November 2005	“ANGLES” program re-named “SURVEY” “ANGLE” program added.
1.5	November 2005	“CIRCLE” program added.
1.6	March 2007	“PT2PLANE” program added.
1.7	November 2007	“SURVEY2D” program added
2.1	August 2008	Introduction extended. “Curve” Program added. “Cut~Area” Program added.
3.0	November 2009	“3D-CFIX” program added. “INT~SECT2” program added.
4.0	May 2013	“MEAN~XY” updated to “MEAN~XYZ” 3D~DIST, PT2LINE program added HAVERSIN, INT~DIST program added INT~SECT renamed INT~BEAR INTSECT2 renamed INT~LINE Progs converted to fx-9860GII
4.1	January 2014	Program “LN2PLANE” added
4.11	February 2014	Dec Deg to D/M/S conversion updated



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